

RESOURCE SHARING

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Outline

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- Resource-dominated circuits.
 - Flat and hierarchical graphs.
 - Functional and memory resources.
- Extensions.
 - Non resource-dominated circuits.
 - Concurrent scheduling and binding.
 - Module selection.

Allocation and binding

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- *Allocation:*
 - Number of resources available.
- *Binding:*
 - Relation between operations and resources.
- *Sharing:*
 - Many-to-one relation.
- *Optimum binding/sharing:*
 - Minimize the resource usage.

Binding

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- Limiting cases:
 - Dedicated resources:
 - * One resource per operation.
 - * No sharing.
 - One multi-task resource:
 - * ALU.
 - One resource per type.

Optimum sharing problem

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- Scheduled sequencing graphs.
 - Operation concurrency well defined.
- Consider *operation types* independently.
 - Problem decomposition.
 - Perform analysis for each resource type.

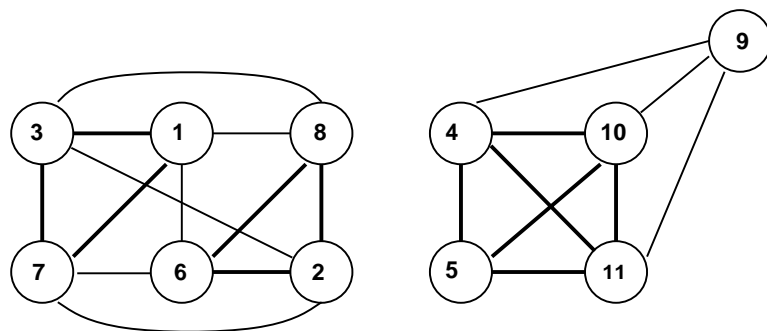
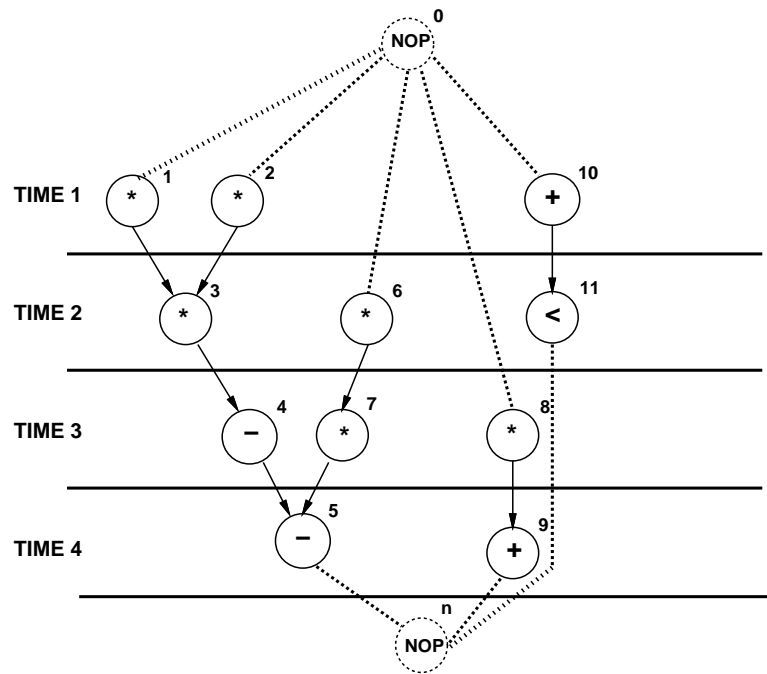
Compatibility and conflicts

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- Operation compatibility:
 - Same type.
 - Non concurrent.
- *Compatibility* graph:
 - Vertices: operations.
 - Edges: compatibility relation.
- *Conflict* graph:
 - Complement of compatibility graph.

Example

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Multiplier

ALU

Algorithmic solution to the optimum binding problem

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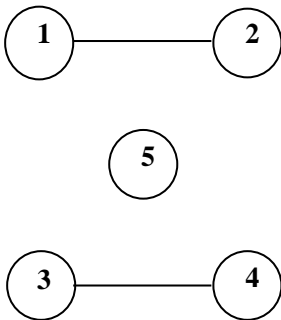
- *Compatibility* graph.
 - Partition the graph into a minimum number of cliques.
 - Find *clique cover number* $\kappa(G_+)$.
- *Conflict* graph.
 - Color the vertices by a minimum number of colors.
 - Find *chromatic number* $\chi(G_-)$.
- NP-complete problems – Heuristic algorithms.

Example

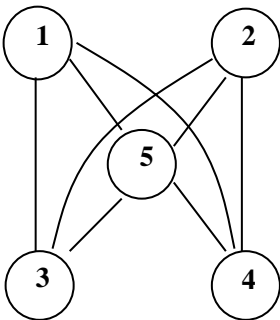
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t1	x=a+b	y=c+d	1	2
t2	s=x+y	t=x-y	3	4
t3	z=a+t		5	

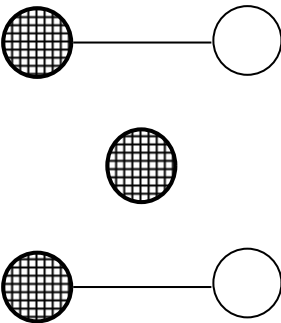
Conflict



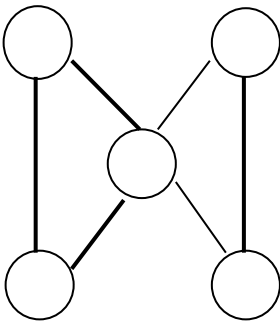
Compatibility



Coloring



Covering



ALU1: 1,3,5

ALU2: 2,4

Left-edge algorithm

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- Input:
 - Set of intervals with *left* and *right* edge.
- Rationale:
 - Sort intervals by *left* edge.
 - Assign non overlapping intervals to first color using the sorted list.
 - When possible intervals are exhausted increase color counter and repeat.

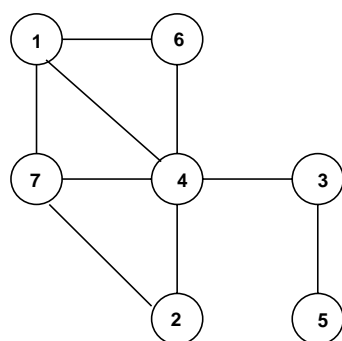
Left-edge algorithm

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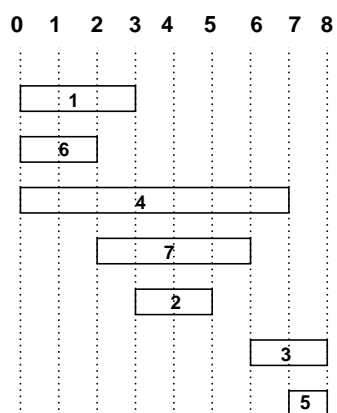
```
LEFT_EDGE( $I$ ) {
    Sort elements of  $I$  in a list  $L$  in ascending order of  $l_i$ ;
     $c = 0$ ;
    while (some interval has not been colored ) do {
         $S = \emptyset$ ;
         $r = 0$ ;
        while (  $\exists s \in L$  such that  $l_s > r$  ) do{
             $s =$  First element in the list  $L$  with  $l_s > r$ ;
             $S = S \cup \{s\}$ ;
             $r = r_s$ ;
            Delete  $s$  from  $L$ ;
        }
         $c = c + 1$ ;
        Label elements of  $S$  with color  $c$ ;
    }
}
```

Example

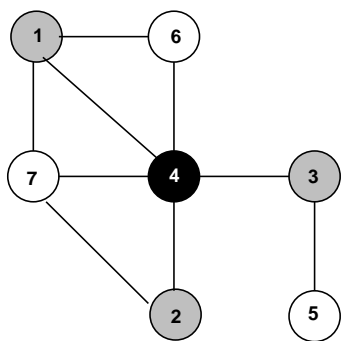
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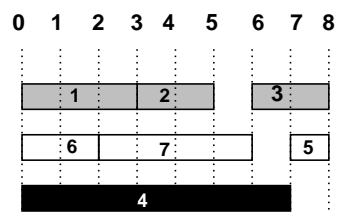
(a)



(b)



(c)



(d)

Register binding problem

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- Given a schedule:
 - *Lifetime intervals* for variables.
 - *Lifetime overlaps*.
- Conflict graph (*interval graph*).
 - Vertices \leftrightarrow variables.
 - Edges \leftrightarrow overlaps.
 - Interval graph.
- Compatibility graph (*comparability graph*).
 - Complement of conflict graph.

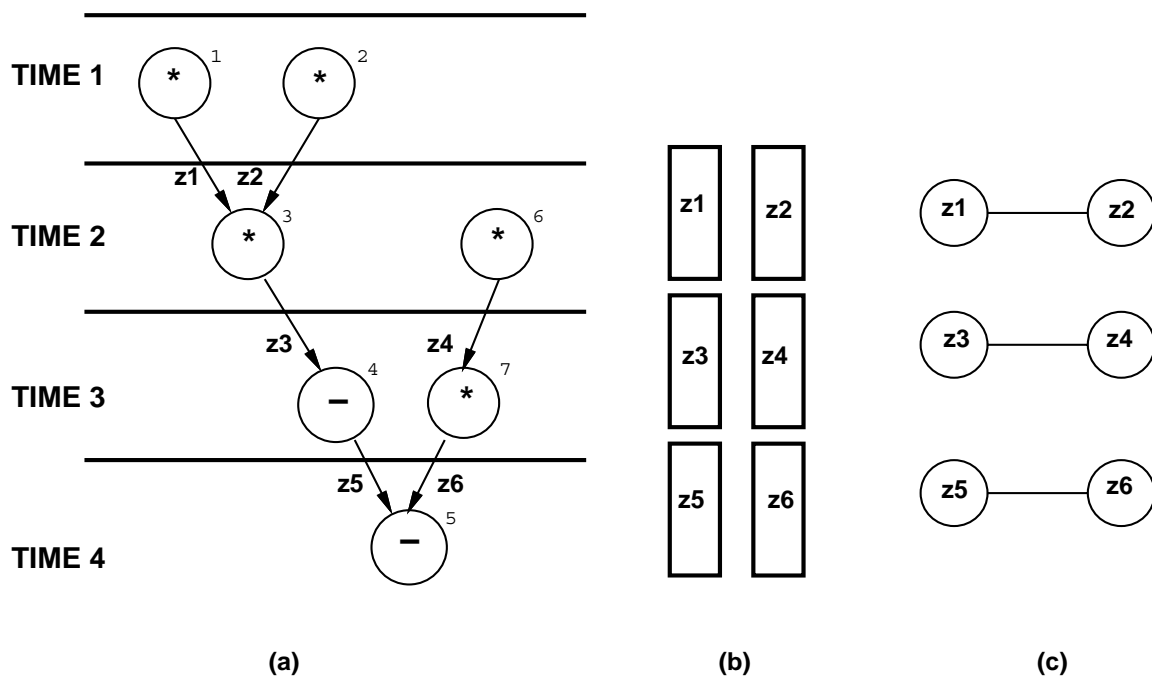
Register sharing data-flow graphs

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- Given:
 - Variable lifetime conflict graph.
- Find:
 - Minimum number of registers storing all the variables.
- Key point:
 - Interval graph:
 - * Left-edge algorithm. (Polynomial-time).

Example

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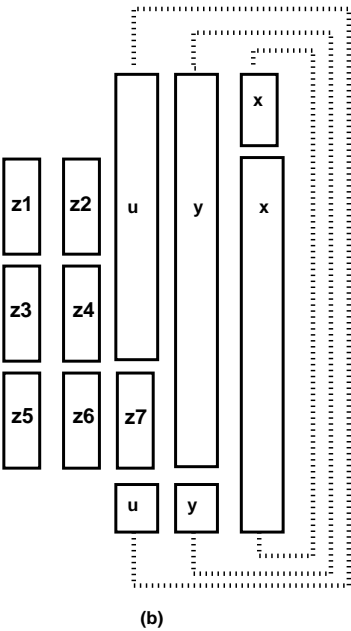
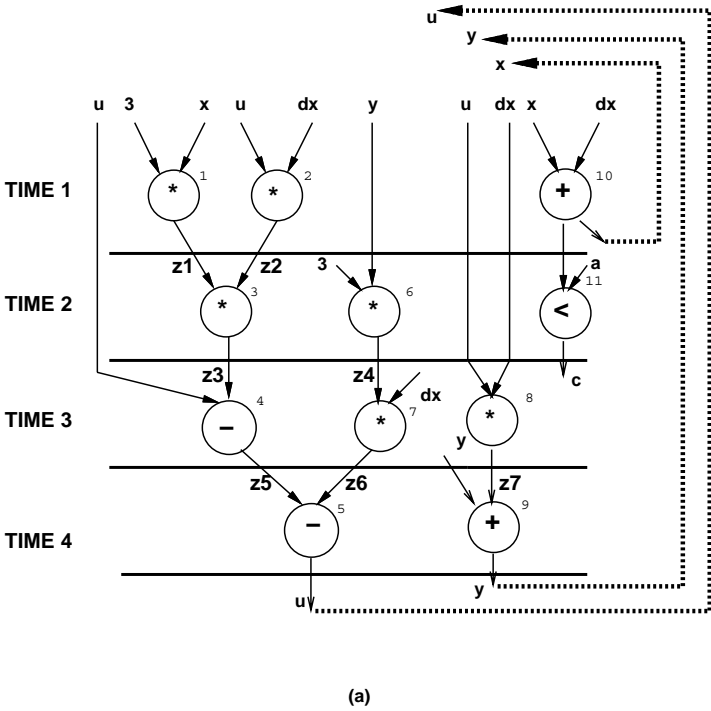
Register sharing general case

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- Iterative constructs:
 - Preserve values across iterations.
 - *Circular-arc* conflict graph:
 - * Coloring is intractable.
- Hierarchical graphs:
 - General conflict graphs:
 - * Coloring is intractable.
- Heuristic algorithms.

Example

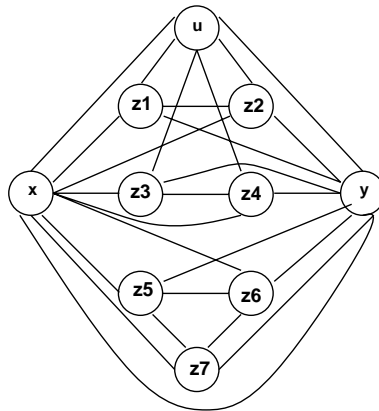
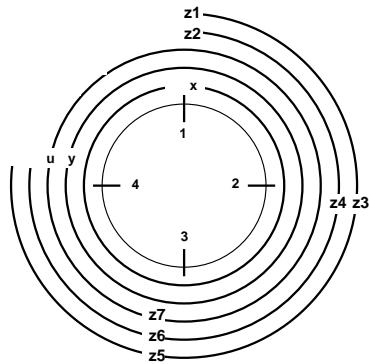
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Example

Variable-lifetimes and circular-arc conflict graph

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Module selection problem

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- Library of resources:
 - More than one resource per type.
- Example:
 - Ripple-carry adder.
 - Carry look-ahead adder.
- Resource modeling:
 - Resource *subtypes* with:
 - * (*area*, *delay*) parameters.

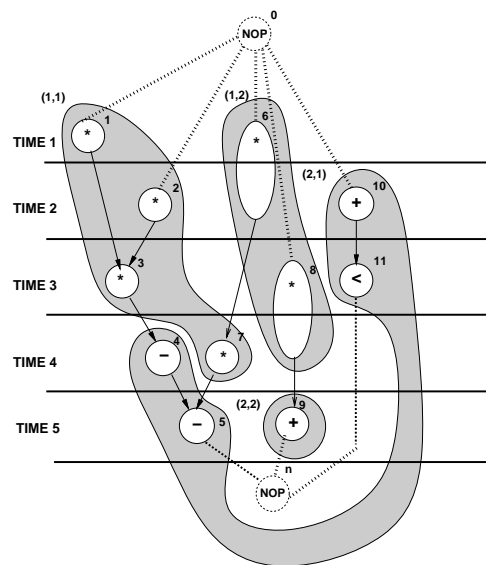
Module selection solution

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- ILP formulation:
 - Decision variables:
 - * Select resource sub-type.
 - * Determine (*area*, *delay*).
- Heuristic algorithms:
 - Determine *minimum latency* with fastest resource subtypes.
 - Recover area by using slower resources on non-critical paths.

Example

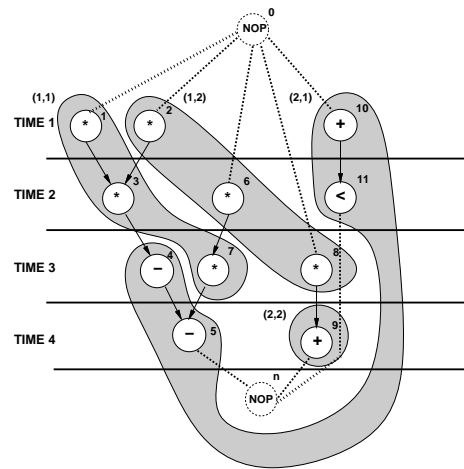
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- Multipliers with:
 - (Area, delay) = (5,1) and (2,2)
- Latency bound of 5.

Example (2)

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- Latency bound of 4.
 - Fast multipliers for $\{v_1, v_2, v_3\}$.
 - Slower multipliers can be used elsewhere.
 - * Less sharing.
- Minimum-area design uses fast multipliers only.

Summary

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- Resource sharing is reducible to coloring/clique-covering.
- Simple for flat graphs.
- Intractable, but still easy in practice, for other graphs.
- More complicated for non resource-dominated circuits.
- Extension: module selection.