

# Lectures on DIFFERENTIAL GEOMETRY AND TOPOLOGY

Manzo Spora

## Lecture VII

\* Differential  $\mathbb{R}$ -forms

As usual  $n \geq 1$

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Let  $\Lambda_p(\mathbb{R}^n)$  denote the  $\binom{n}{k}$  dimensional space of  $\mathbb{R}$ -forms on  $T_p \mathbb{R}^n$  [notice the slight change of notation]

A basis thereof is given by  $(dx^{i_1}|_p \wedge \dots \wedge dx^{i_k}|_p)$

$$i_1 < i_2 < \dots < i_k \quad , \quad i_j \in \{1, 2, \dots, n\}$$

notice the hyper indices appended to coordinates: this is in view of applying tensor notation

Obviously

$$dx^{i_1}|_p \wedge \dots \wedge dx^{i_k}|_p = dx^{i_1} \wedge \dots \wedge dx^{i_k}|_p$$

Also set  $dx^{i_1} \wedge \dots \wedge dx^{i_k} =: dx^I$        $I = (i_1, \dots, i_k)$

(abbreviated notation)

The differential  $\mathbb{R}$ -forms (on  $\mathbb{R}^n$ ) are then the (smooth) functions

$$\omega: \mathbb{R}^n \ni p \longmapsto \omega_I(p) dx^I$$

$$= \omega_{i_1 \dots i_k}(p) dx^{i_1} \wedge \dots \wedge dx^{i_k}|_p$$

← Einstein

← sometimes, for clarity,  $\Sigma$  will be added

$$\omega_I \equiv \omega_{i_1 \dots i_k} \in \Lambda^k(\mathbb{R}^n)$$

smooth function

Notation:  $\Lambda^k(\mathbb{R}^n)$

Again a bundle interpretation can be given, but for the time being we do not further delve into it.

### \* Properties of differential forms

(we shall often omit the adjective "differential")

Given  $\mathbb{R}$ -forms  $\omega_1 = a_I dx^I$ ,  $\omega_2 = b_I dx^I$ ,

their linear combination (with  $\alpha, \beta \in \Lambda^0(\mathbb{R}^n)$ ) is

$$\alpha \omega^1 + \beta \omega^2 = (\alpha a_I + \beta b_I) dx^I$$

(as in the algebraic case: every thing is carried out pointwise)

The wedge product between  $\omega_1$  ( $k$ -form)

and  $\omega_2$  ( $l$ -form),  $\omega_1 = a_I dx^I$   
 $\omega_2 = b_J dx^J$

(again defined pointwise) reads:

$$\omega_1 \wedge \omega_2 = a_I b_J dx^I \wedge dx^J$$

Let us check that

$$(a) \quad \overset{k}{\omega} \wedge \overset{s}{\varphi} \wedge \overset{r}{\eta} = \omega \wedge (\varphi \wedge \eta)$$

$$\text{" } a_I dx^I \text{" } \text{" } b_J dx^J \text{" } \text{" } c_K dx^K \text{"}$$

(associativity, therefore

one can safely write  $\omega \wedge \varphi \wedge \eta$  without ambiguity)

$$(b) \quad \omega \wedge (\varphi + \eta) = \omega \wedge \varphi + \omega \wedge \eta \quad (\text{easy})$$

$\text{if } r=s$

$$(c) \quad \overset{k}{\omega} \wedge \overset{s}{\varphi} = (-1)^{ks} \overset{s}{\varphi} \wedge \overset{k}{\omega} \quad \text{graded commutativity}$$

Notice that  $\mathcal{X}(\mathbb{R}^n)$  (vector fields) and  $\Lambda^k(\mathbb{R}^n)$  are in fact modules over  $\Lambda^0(\mathbb{R}^n)$   
 $X \in \mathcal{X}(\mathbb{R}^n) \Rightarrow fX \in \mathcal{X}(\mathbb{R}^n)$   
 $\omega \in \Lambda^k(\mathbb{R}^n) \Rightarrow f\omega \in \Lambda^k(\mathbb{R}^n)$   
 etc.

Proof of (a):  $(\omega \wedge \varphi) \wedge \psi = (a_I dx^I \wedge b_J dx^J) \wedge c_K dx^K =$   
 $= (a_I b_J dx^I \wedge dx^J) \wedge (c_K dx^K) = a_I b_J c_K dx^I \wedge dx^J \wedge dx^K =$   
 $= \text{r.h.s.}$

Proof of (c):  $\omega \wedge \varphi = a_I b_J dx^{i_1} \dots dx^{i_k} \wedge dx^{j_1} \dots dx^{j_s}$   
 $= - a_I b_J dx^{i_1} \dots dx^{j_1} \wedge dx^{i_k} \dots dx^{j_s}$

$\Rightarrow$  There are  $\underbrace{\mathbb{R} + \mathbb{R} + \dots + \mathbb{R}}_{s \text{ times}} = \mathbb{R} \cdot s$  sign changes before

obtaining  $\varphi \wedge \omega$ , yielding the  $(-1)^{\mathbb{R} \cdot s}$  factor in the r.h.s.

Notice that in general  $\omega \wedge \omega \neq 0$

(If  $\omega \in \Delta^k(\mathbb{R}^n)$ ,  $\mathbb{R}$  odd, then  $\omega \wedge \omega = (-1)^{\mathbb{R}^2} \omega \wedge \omega$   
 $= -\omega \wedge \omega \Rightarrow \omega \wedge \omega = 0$ )

If  $\mathbb{R}$  is even, then one has a tautology:  $\omega \wedge \omega = \omega \wedge \omega$

Example: In  $\mathbb{R}^4$ , take  $\omega = dx^1 \wedge dx^2 + dx^3 \wedge dx^4 \in \Delta^2(\mathbb{R}^4)$   
 This is an example of symplectic form

Then  $\omega \wedge \omega = \underbrace{dx^1 \wedge dx^2 \wedge dx^1 \wedge dx^2}_{=0} + \underbrace{dx^1 \wedge dx^2 \wedge dx^3 \wedge dx^4}_{\neq 0}$   
 $+ dx^3 \wedge dx^4 \wedge dx^1 \wedge dx^2 + \underbrace{dx^3 \wedge dx^4 \wedge dx^3 \wedge dx^4}_{=0}$   
 $= dx^1 \wedge dx^2 \wedge dx^3 \wedge dx^4 = 2 \underbrace{dx^1 \wedge dx^2 \wedge dx^3 \wedge dx^4}_{\text{volume form on } \mathbb{R}^4}$

\* Pull-back of differential forms

Given a smooth function  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ ,

and a  $k$ -form  $\omega \in \Lambda^k(\mathbb{R}^m)$ , one can construct

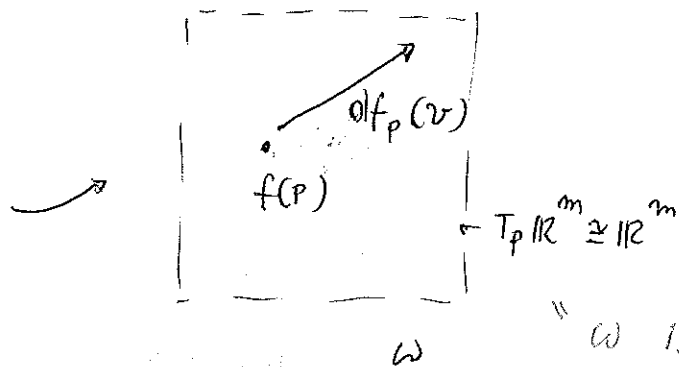
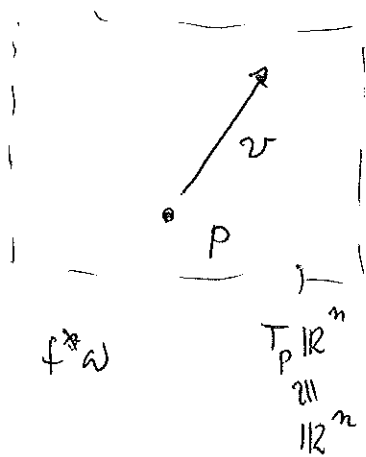
a  $k$ -form  $f^*\omega \in \Lambda^k(\mathbb{R}^n)$  (pull-back of  $\omega$  via  $f$ )

in the following guise:

pointwise, the  $k$ -form is to be evaluated  
 $k$ -tuple of vectors from  $T_p \mathbb{R}^n$

$$(f^*\omega)(p)(v_1, \dots, v_k) := \omega(f(p))(df_p(v_1), \dots, df_p(v_k))$$

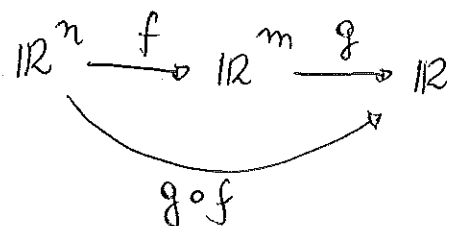
$\uparrow$   $T_p \mathbb{R}^n$   $\rightarrow$  differential of  $f$   
 $\uparrow$   $T_{f(p)} \mathbb{R}^m$



" $\omega$  is pulled back to  $f^*\omega$ "

If  $g \in \Lambda^0(\mathbb{R}^m)$  (a smooth function  $g: \mathbb{R}^m \rightarrow \mathbb{R}$ )

set  $f^*g := g \circ f$



Let us interpret the above formula

Pick  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

(one can in fact work on  $U \subset \mathbb{R}^n$ )  
 $\downarrow$   
 open

concretely

$$\begin{cases} y^1 = f^1(\alpha^1 \dots \alpha^n) \\ y^2 = f^2(\alpha^1 \dots \alpha^n) \\ \vdots \\ y^m = f^m(\alpha^1 \dots \alpha^n) \end{cases} \quad y = f(\alpha)$$

Now:

$$(f^* dy^i)(v) \stackrel{\text{def}}{=} dy^i(df(v)) \stackrel{\text{Chain rule}}{=} d(y^i \circ f)(v)$$

def of pull-back

$$= d(f^* y^i)(v) = df^i(v)$$

$y^i \circ f = f^i$  as a function of  $\alpha$

Therefore, operationally, if  $\omega = a_I(y) dy^I$ ,

$$\text{then } f^* \omega = a_I(f(\alpha)) df^I$$

$$dy^I = \frac{\partial y^I}{\partial \alpha^J} d\alpha^J \quad \leftarrow \text{"partial Jacobians"}$$

If  $I = i, J = j$   
 (single indices)

$\left( \frac{\partial y^i}{\partial \alpha^j} \right)$  is the Jacobian matrix of  $df$

$$\omega = a_I dy^I \longmapsto f^* \omega = \underbrace{\left( a_I \frac{\partial y^I}{\partial \alpha^J} \right)}_{a'_J} d\alpha^J$$

see how practical tensor notation is!

see also below

Example (extremely important)

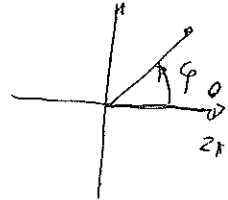
$$1. \quad \omega = \frac{-y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$$

(in  $U = \{ r > 0, 0 < \varphi < 2\pi \}$   
polar coord'n-tes

defined for  $(x, y) \neq (0, 0)$

$$\text{Let } f: \begin{cases} x = r \cos \varphi \\ y = r \sin \varphi \end{cases}$$

$$x^2 + y^2 = r^2$$



Then  $f^* \omega = \dots = d\varphi$  angular form

$$\varphi = \arctan \frac{y}{x} \quad x \neq 0$$

It is instructive to compute this directly

$$dx = dr \cos \varphi - r \sin \varphi d\varphi$$

$$= \cos \varphi dr - r \sin \varphi d\varphi$$

$$dy = \sin \varphi dr + r \cos \varphi d\varphi$$

$$\frac{-r \sin \varphi}{r^2} (\cos \varphi dr - r \sin \varphi d\varphi) + \frac{r \cos \varphi}{r^2} (\sin \varphi dr + r \cos \varphi d\varphi)$$

these two terms cancel out

$$= (\underbrace{\sin^2 \varphi + \cos^2 \varphi}_1) d\varphi = d\varphi$$

Other examples

Summs over  $i_1 \dots i_n$  are omitted

$$2. \quad dy^{i_1} \wedge \dots \wedge dy^{i_n} = \frac{\partial y^{i_1}}{\partial x^{l_1}} dx^{l_1} \wedge \dots \wedge \frac{\partial y^{i_n}}{\partial x^{l_n}} dx^{l_n}$$

$$= \frac{\partial (y^{i_1} \dots y^{i_n})}{\partial (x^{l_1} \dots x^{l_n})} dx^{l_1} \wedge \dots \wedge dx^{l_n}$$

"partial Jacobians"

This is clear from the very definition of determinant involving the appropriate sums over permutations, weighted with  $(-1)^\sigma$ .  
Whenever two equal  $dx$  appear, one gets zero by skew-symmetry

Take, for instance

2'  $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\begin{cases} x = x(u, v) \\ y = y(u, v) \end{cases}$$

$\omega = dx \wedge dy$   
 "area 2-form"  
 (oriented)

$$f^* \omega = \frac{\partial(x, y)}{\partial(u, v)} du \wedge dv$$

check this directly:

without  $| \cdot |$ :  
 one has an oriented area element

$$\begin{cases} dx = x_u du + x_v dv \\ dy = y_u du + y_v dv \end{cases}$$

$$dx \wedge dy = (x_u y_v - x_v y_u) du \wedge dv$$

we have omitted the symbol  $f^*$

$$\frac{\partial(x, y)}{\partial(u, v)}$$

2''  $f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$

$$dy^1 \wedge dy^2 = \frac{\partial y^1}{\partial x^1} \frac{\partial y^2}{\partial x^2} dx^1 \wedge dx^2 + \dots$$

$$= \left( \frac{\partial y^1}{\partial x^1} \frac{\partial y^2}{\partial x^2} - \frac{\partial y^2}{\partial x^1} \frac{\partial y^1}{\partial x^2} \right) dx^1 \wedge dx^2 + \text{similar terms}$$

$$\begin{vmatrix} \frac{\partial y^1}{\partial x^1} & \frac{\partial y^1}{\partial x^2} \\ \frac{\partial y^2}{\partial x^1} & \frac{\partial y^2}{\partial x^2} \end{vmatrix}$$

$$\frac{\partial(y^1, y^2)}{\partial(x^1, x^2)}$$

3.  $\varphi: \mathbb{R}^2 \rightarrow \mathbb{R}^3$   $\varphi \equiv \underline{r}$   
 $(u, v) \mapsto (x, y, z)$

$\underline{F}$ : flux 2-form ( $\in \Lambda^2(\mathbb{R}^3)$ )

$$\underline{F} = F_1 dy \wedge dz + F_2 dz \wedge dx + F_3 dx \wedge dy$$

$$\varphi^* \underline{F} = \left[ F_1(x(u, v), y(u, v), z(u, v)) \frac{\partial(y, z)}{\partial(u, v)} + F_2 \frac{\partial(z, x)}{\partial(u, v)} + F_3 \frac{\partial(x, y)}{\partial(u, v)} \right] du \wedge dv = \underline{F} \cdot \underline{d\sigma}$$

area element

$$= \langle \underline{F}, \underline{r}_u \times \underline{r}_v \rangle du \wedge dv = \int \underline{F} \cdot \underline{r}_u \times \underline{r}_v du \wedge dv$$

# \* Properties of pull-back ("functoriality")

compatibility with the various operations

$$(a) \quad f^*(\omega + \varphi) = f^*\omega + f^*\varphi$$

↑  
k-forms

(easy)

$$(b) \quad f^*(g \cdot \omega) = f^*(g) f^*\omega$$

$\begin{matrix} \mathbb{R}^n \\ \downarrow \\ \mathbb{R}^m \end{matrix}$ 
 $\begin{matrix} \mathbb{R}^m \\ \downarrow \\ \mathbb{R}^k \end{matrix}$

$$\mathbb{R}^n \xrightarrow{f} \mathbb{R}^m \xrightarrow{g} \mathbb{R}^k$$

(easy)

$$(c) \quad f^*(\varphi_1 \wedge \varphi_2 \wedge \dots \wedge \varphi_k) = f^*\varphi_1 \wedge f^*\varphi_2 \wedge \dots \wedge f^*\varphi_k$$

$\begin{matrix} \swarrow & \downarrow & \searrow \\ \text{1-forms} & & \end{matrix}$

this will hold in general

let us prove it:  $f^*(\varphi_1 \wedge \dots \wedge \varphi_k)(v_1, \dots, v_k) =$

= ... evaluated at p

$$= (\varphi_1 \wedge \dots \wedge \varphi_k)(df(v_1), \dots, df(v_k))$$

$$= \det(\varphi_i(df(v_j))) = \det(\underbrace{f^*\varphi_i(v_j)})$$

recall!

$$= (f^*\varphi_1 \wedge \dots \wedge f^*\varphi_k)(v_1, \dots, v_k) \quad \square$$

(d) in general:  $f^*(\omega \wedge \varphi) = f^*\omega \wedge f^*\varphi$

Proof.  $\omega = a_I dy^I, \varphi = b_J dy^J$

$$f^*(\omega \wedge \varphi) = f^*(a_I b_J dy^I \wedge dy^J) = a_I(f^! \dots f^!) b_J(f^! \dots f^!) df^I \wedge df^J$$

$\Delta$  (d) is true

for products of 1-forms, see (c)

$$= f^*\omega \wedge f^*\varphi$$

□

recall the operational interpretation VII-8



(e)  $(f \circ g)^* \omega = g^*(f^* \omega)$  two step pulling-back

direct pulling-back  $\nearrow$

(beware!)

$\mathbb{R}^p \xrightarrow{g} \mathbb{R}^n \xrightarrow{f} \mathbb{R}^m$

$$(f \circ g)^* \omega = a_I ((f \circ g)^I) d(f \circ g)^I \quad \xleftarrow{g^*} \quad \xleftarrow{f^*}$$

chain rule:  $d(f \circ g) = df \circ dg$

$$= a_I (f^1(g^1 \dots g^n) \dots f^m(g^1 \dots g^n)) \times df^I(dg^1 \dots dg^n)$$

$$= g^*(f^* \omega)$$

just an application of the chain rule

□