

Second Partial Test in Optimization

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Exercise 1. Consider the following control system in \mathbb{R}^2 :

$$\begin{cases} \dot{x}_1(t) = x_1(t) - 3x_2(t); \\ \dot{x}_2(t) = u(t) + x_1(t) - 4x_2(t). \end{cases}$$

where $u(\cdot) \in \mathcal{U} := \{u : \mathbb{R} \rightarrow U := [-1, 1] \text{ measurable}\}$, and the problem $\max_{u \in \mathcal{U}} x_1(T)$.

- (1) Write the adjoint system with terminal conditions and solve it explicitly;
- (2) Apply Pontryagin's Maximum Principle to determine the candidates and establish whether they are optimal in the case $T = \sqrt{2}\pi$.

Exercise 2. For $i = 1, 2, 3$, consider the following problem: minimize the functional

$$\int_0^1 (t^2 x'(t) + 2x'(t)^2 + x(t)^2 x'(t) + 2x(t)^2 + 3x(t)) dt, \quad x(\cdot) \in \mathcal{C}_i,$$

where

$$\mathcal{C}_1 := C^2(\mathbb{R}), \quad \mathcal{C}_2 := \{x(\cdot) \in C^2(\mathbb{R}) : x(0) = 0, x(1) = 1\}, \quad \mathcal{C}_3 := \left\{ x(\cdot) \in C^2(\mathbb{R}) : \int_0^1 x(t) dt = 1 \right\}.$$

In each case establish whether the infimum is attained or not, and in the positive case find explicitly the point of minimum.

Exercise 3.

- (1) State and prove Ekeland's Variational Principle.
- (2) Formulate and discuss the brachistochrone problem.
- (3) For any $n \in \mathbb{N}$, let $p_n : \text{Mat}_{n \times n}(\mathbb{R}) \rightarrow \text{Mat}_{n \times n}(\mathbb{R})$ defined by $p_n(A) = A^n$ for all matrices $A \in \text{Mat}_{n \times n}(\mathbb{R})$, where A^n denotes the usual product of matrices between n copies of A . Compute the Fréchet differential of p_n w.r.t. a chosen norm on $\text{Mat}_{n \times n}(\mathbb{R})$. Does the differential depend on the norm chosen on $\text{Mat}_{n \times n}(\mathbb{R})$?
- (4) State Pontryagin's Maximum Principle for a Mayer control problem.
- (5) Provide a sufficient condition granting the convexity of the reachable set of a control system from a point.